



INSTALLATION AND OPERATION

## USER MANUAL

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# UM981S

BDS/GPS/GLONASS/Galileo/QZSS

All-constellation Multi-frequency  
RTK/INS Integrated Positioning Module

## Revision History

| Version | Revision History                                                                                                                        | Date       |
|---------|-----------------------------------------------------------------------------------------------------------------------------------------|------------|
| R1.0    | First release                                                                                                                           | Oct., 2024 |
| R1.1    | Updated <b>3.5 Recommended Footprint on the PCB</b> .<br>Updated the stencil thickness suggestion in <b>4 Production Requirements</b> . | Mar., 2025 |

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## Foreword

This document describes the hardware information, specifications, packaging and the use of Unicore UM981S modules.

### Target Readers

This document is written for technicians who are familiar with GNSS modules.

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# 1 Introduction

UM981S is a new generation GNSS high precision RTK/INS integrated positioning module from Unicore. It can track BDS/GPS/GLONASS/Galileo/QZSS all constellations and multiple frequencies. The module is mainly used in high precision applications and is particularly suitable for surveying and mapping.

UM981S is based on NebulasIV™, a GNSS SoC which integrates RF, baseband and high precision algorithm. Besides, the SoC integrates a dual-core CPU, a high speed floating point processor and an RTK co-processor. It is processed with 22 nm low power design and has 1408 channels, being able to output 100 Hz IMU raw data and up to 50 Hz\* RTK positioning data, providing powerful data processing ability. With the built-in JamShield anti-jamming technology, UM981S has improved the performance of multi-mode multi-frequency RTK solution, ensuring fast RTK initialization speed, high accuracy of measurement and high reliability even in signal-challenging environments such as urban canyons and tree shades. UM981S has also integrated an IMU for surveying and mapping applications, supporting tilt compensation.

UM981S has various interfaces such as UART, I<sup>2</sup>C\* and SPI\*, as well as 1PPS, EVENT and CAN\*, which meets customers' needs in different applications.

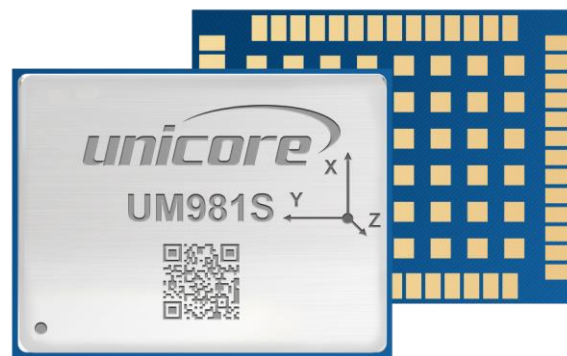


Figure 1-1 UM981S Module

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\* Data update rate can reach 50 Hz after firmware upgrade.

\* I<sup>2</sup>C, SPI and CAN are reserved interfaces, not supported currently.

### 1.1 Key Features

- Based on the new generation GNSS SoC - NebulasIV™, which integrates RF, baseband and high precision algorithm
- All-constellation multi-frequency RTK engine and advanced RTK processing technology
- Instantaneous RTK initialization technology
- Tracking different frequencies separately with 60 dB narrowband anti-jamming technology
- 100 Hz IMU raw data output and GNSS & IMU integrated data output, up to 50 Hz\* RTK positioning data output
- Supports tilt compensation
- Supports B2b-PPP service and E6-HAS service

### 1.2 Key Specifications

Table 1-1 Technical Specifications

| Basic Information |                                                                                                                                                                       |
|-------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Channels          | 1408 channels, based on NebulasIV™                                                                                                                                    |
| Constellations    | BDS/GPS/GLONASS/Galileo/QZSS                                                                                                                                          |
| Frequencies       | BDS: B1I, B2I, B3I, B1C, B2a, B2b<br>GPS: L1 C/A, L1C, L2P (Y), L2C, L5<br>GLONASS: G1, G2, G3<br>Galileo: E1, E5a, E5b, E6<br>QZSS: L1C/A, L1C, L2C, L5<br>NavIC: L5 |
| Power             |                                                                                                                                                                       |
| Voltage           | +3.0 V ~ +3.6 V DC                                                                                                                                                    |
| Power Consumption | 480 mW (Typical)                                                                                                                                                      |
| Performance       |                                                                                                                                                                       |

|                                         |                                             |                                                        |         |         |
|-----------------------------------------|---------------------------------------------|--------------------------------------------------------|---------|---------|
| Positioning Accuracy                    | Single Point Positioning <sup>1</sup> (RMS) | Horizontal: 1.5 m                                      |         |         |
|                                         |                                             | Vertical: 2.5 m                                        |         |         |
|                                         | DGPS <sup>1,2</sup> (RMS)                   | Horizontal: 0.4 m                                      |         |         |
|                                         |                                             | Vertical: 0.8 m                                        |         |         |
|                                         | RTK <sup>1,2</sup> (RMS)                    | Horizontal: 0.8 cm + 1 ppm                             |         |         |
|                                         |                                             | Vertical: 1.5 cm + 1 ppm                               |         |         |
|                                         | Tilt Measurement                            | 10 mm + 0.7 mm/°tilt<br>(accuracy < 2.5 cm within 30°) |         |         |
| Attitude Accuracy                       | Heading                                     | 0.3°                                                   |         |         |
|                                         | Roll                                        | 0.2°                                                   |         |         |
|                                         | Pitch                                       | 0.2°                                                   |         |         |
| Observation Accuracy (RMS)              | BDS                                         | GPS                                                    | GLONASS | Galileo |
| B1I/B1C/L1C/L1 C/A/G1/E1 Pseudorange    | 10 cm                                       | 10 cm                                                  | 10 cm   | 10 cm   |
| B1I/B1C/L1C/L1 C/A/G1/E1 Carrier Phase  | 1 mm                                        | 1 mm                                                   | 1 mm    | 1 mm    |
| B3I/L2P(Y)/L2C/G2/E6 Pseudorange        | 10 cm                                       | 10 cm                                                  | 10 cm   | 10 cm   |
| B3I/L2P(Y)/L2C/G2/E6 Carrier Phase      | 1 mm                                        | 1 mm                                                   | 1 mm    | 1 mm    |
| B2I/B2a/B2b/L5/G3/E5a/E5b Pseudorange   | 10 cm                                       | 10 cm                                                  | 10 cm   | 10 cm   |
| B2I/B2a/B2b/L5/G3/E5a/E5b Carrier Phase | 1 mm                                        | 1 mm                                                   | 1 mm    | 1 mm    |

<sup>1</sup> Test results may be biased due to atmospheric conditions, baseline length, GNSS antenna type, multipath effect, number of visible satellites, and satellite geometry.

<sup>2</sup> The measurement uses 1 km baseline and a receiver with good antenna performance, regardless of possible errors of antenna phase center offset.

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|                                              |                                                                  |
|----------------------------------------------|------------------------------------------------------------------|
| Time Pulse Accuracy (RMS)                    | 20 ns                                                            |
| Velocity Accuracy <sup>3</sup> (RMS)         | 0.03 m/s                                                         |
| Time to First Fix <sup>4</sup> (TTFF)        | Cold Start < 12 s                                                |
|                                              | Hot Start < 4 s                                                  |
| GNSS Initialization Time <sup>1</sup>        | < 5 s (Typical)                                                  |
| GNSS Initialization Reliability <sup>1</sup> | > 99.9%                                                          |
| Data Update Rate <sup>5</sup>                | 100 Hz IMU raw data output and GNSS & IMU integrated data output |
|                                              | 50 Hz RTK positioning data output                                |
| Differential Data                            | RTCM 3.X                                                         |
| Data Format                                  | NMEA-0183, Unicore                                               |
| Physical Characteristics                     |                                                                  |
| Package                                      | 54 pin LGA                                                       |
| Dimensions                                   | 22 mm × 17 mm × 2.6 mm                                           |
| Weight                                       | 1.91 g ± 0.03 g                                                  |
| Environmental Specifications                 |                                                                  |
| Operating Temperature                        | -40 °C ~ +85 °C                                                  |
| Storage Temperature                          | -55 °C ~ +95 °C                                                  |
| Humidity                                     | 95% No condensation                                              |
| Vibration                                    | GJB150.16A-2009, MIL-STD-810F                                    |
| Shock                                        | GJB150.18A-2009, MIL-STD-810F                                    |
| Functional Ports                             |                                                                  |

<sup>3</sup> Open sky, unobstructed scene, 99% @ static.

<sup>4</sup> -130dBm @ more than 12 available satellites.

<sup>5</sup> The 50 Hz data update rate is supported after firmware upgrade.

UART x 3

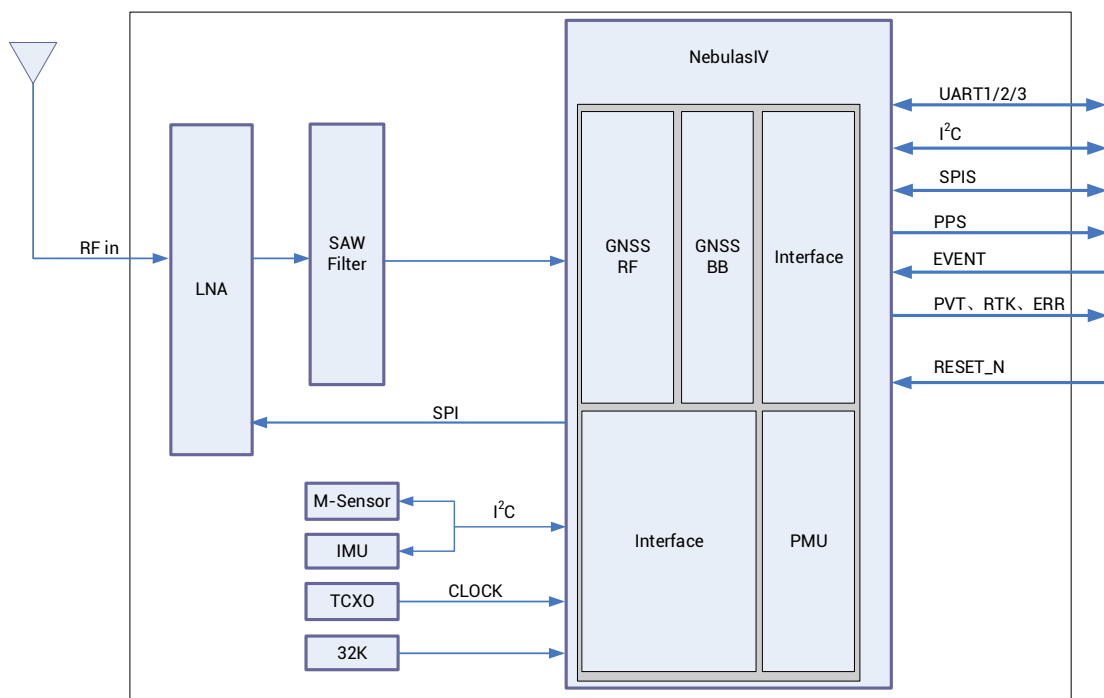
$$|{}^2C^* \times 1$$
$$SPI^* \times 1$$

Slave

$$\text{CAN}^* \times 1$$

Shared with UART3

### 1.3 Block Diagram



### Figure 1-2 UM981S Block Diagram

- **RF Part**

The receiver gets filtered and enhanced GNSS signals from the antenna via a coaxial cable. The RF part converts the RF input signals into the IF signals, and converts IF analog signals into digital signals required for NebulasIV™ chip (UC9810).

- **NebulasIV™ SoC (UC9810)**

NebulasIV (UC9810) is Unicore's new generation high precision GNSS SoC with 22 nm low power design, supporting all constellations and all frequencies with 1408 channels.

\* I2C, SPI and CAN are reserved interfaces, not supported currently.

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It integrates a dual-core CPU, a high speed floating point processor and an RTK co-processor, which can fulfill the high precision baseband processing and RTK positioning on a single chip.

- **External Interfaces**

The external interfaces of UM981S include UART, I<sup>2</sup>C\*, SPI\*, CAN\*, PPS, EVENT, RTK\_STAT, PVT\_STAT, ERR\_STAT, RESET\_N, etc.

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\* I<sup>2</sup>C, SPI, CAN: reserved interfaces, not supported currently.

## 2 Hardware

### 2.1 Pin Definition

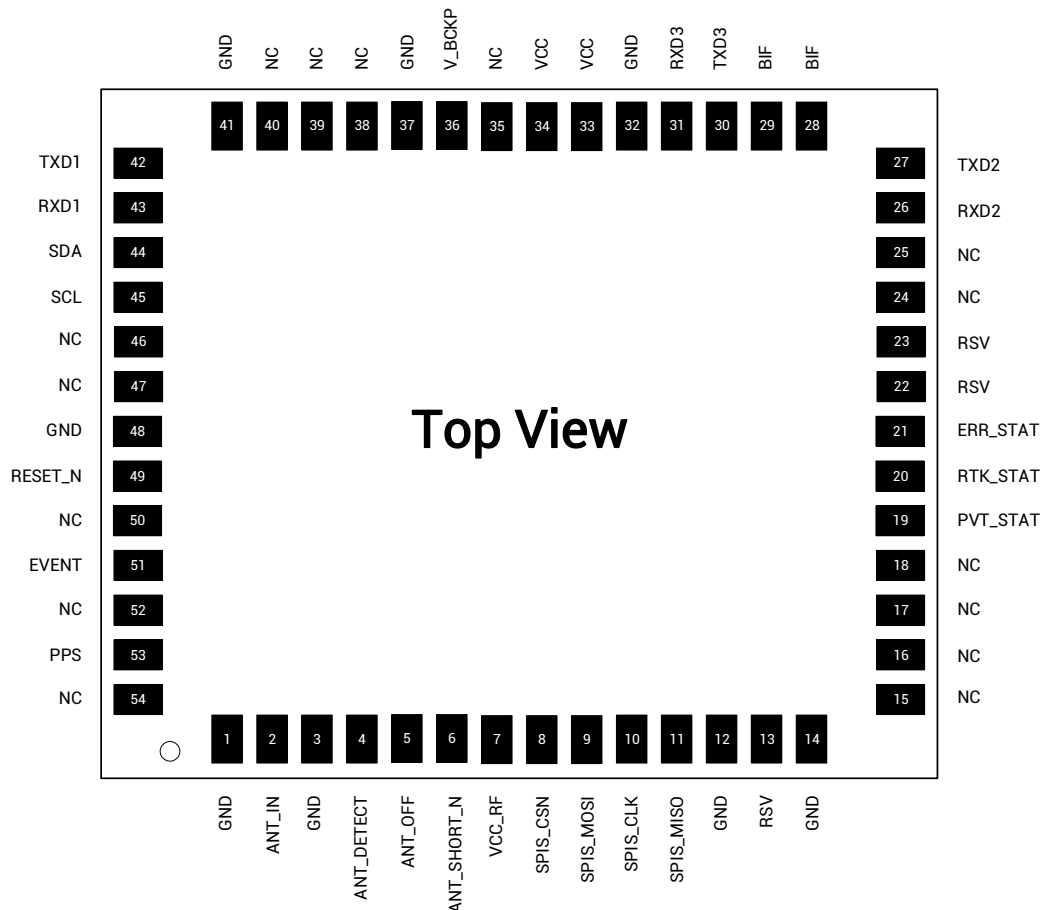


Figure 2-1 UM981S Pin Definition

Table 2-1 Pin Description

| No. | Pin         | I/O | Description                                 |
|-----|-------------|-----|---------------------------------------------|
| 1   | GND         | —   | Ground                                      |
| 2   | ANT_IN      | I   | GNSS antenna signal input                   |
| 3   | GND         | —   | Ground                                      |
| 4   | ANT_DETECT  | I   | Antenna signal detection                    |
| 5   | ANT_OFF     | O   | Disable external LNA                        |
| 6   | ANT_SHORT_N | I   | Antenna short circuit detection; active low |

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| No. | Pin                 | I/O | Description                                                                                                            |
|-----|---------------------|-----|------------------------------------------------------------------------------------------------------------------------|
| 7   | VCC_RF <sup>6</sup> | O   | External LNA power supply                                                                                              |
| 8   | SPIS_CSN            | I   | Chip select pin for SPI slave                                                                                          |
| 9   | SPIS_MOSI           | I   | Master Out / Slave In. This pin is used to receive data in slave mode.                                                 |
| 10  | SPIS_CLK            | I   | Clock input pin for SPI slave                                                                                          |
| 11  | SPIS_MISO           | O   | Master In / Slave Out. This pin is used to transmit data in slave mode.                                                |
| 12  | GND                 | —   | Ground                                                                                                                 |
| 13  | RSV                 | —   | Reserved; must be floating                                                                                             |
| 14  | GND                 | —   | Ground                                                                                                                 |
| 15  | NC                  | —   | No connection inside; leave floating                                                                                   |
| 16  | NC                  | —   | No connection inside; leave floating                                                                                   |
| 17  | NC                  | —   | No connection inside; leave floating                                                                                   |
| 18  | NC                  | —   | No connection inside; leave floating                                                                                   |
| 19  | PVT_STAT            | O   | PVT status: active high;<br>Outputs high when positioning and low when not positioning                                 |
| 20  | RTK_STAT            | O   | RTK status: active high;<br>Outputs high for RTK fixed solution and low for other positioning status or no positioning |
| 21  | ERR_STAT            | O   | Error status: active high;<br>Outputs high when failing self-test and low when passing self-test                       |
| 22  | RSV                 | —   | Reserved; must be floating                                                                                             |
| 23  | RSV                 | —   | Reserved; must be floating                                                                                             |

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<sup>6</sup> Not recommended to use VCC\_RF as ANT\_BIAS to feed the antenna. See section 3.2 for more details.

| No. | Pin    | I/O | Description                                                                                                                                                                                                                                                                                              |
|-----|--------|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 24  | NC     | —   | No connection inside; leave floating                                                                                                                                                                                                                                                                     |
| 25  | NC     | —   | No connection inside; leave floating                                                                                                                                                                                                                                                                     |
| 26  | RXD2   | I   | COM2 input, LVTTTL                                                                                                                                                                                                                                                                                       |
| 27  | TXD2   | O   | COM2 output, LVTTTL                                                                                                                                                                                                                                                                                      |
| 28  | BIF    | —   | Built-in function; recommended to add a through-hole testing point and a 10 kΩ pull-up resistor; cannot connect ground or power supply or input/output data, but can be floating                                                                                                                         |
| 29  | BIF    | —   | Built-in function; recommended to add a through-hole testing point and a 10 kΩ pull-up resistor; cannot connect ground or power supply or input/output data, but can be floating                                                                                                                         |
| 30  | TXD3   | O   | COM3 output, can be used as CAN TXD, LVTTTL                                                                                                                                                                                                                                                              |
| 31  | RXD3   | I   | COM3 input, can be used as CAN RXD, LVTTTL                                                                                                                                                                                                                                                               |
| 32  | GND    | —   | Ground                                                                                                                                                                                                                                                                                                   |
| 33  | VCC    | I   | Power supply                                                                                                                                                                                                                                                                                             |
| 34  | VCC    | I   | Power supply                                                                                                                                                                                                                                                                                             |
| 35  | NC     | —   | No connection inside; leave floating                                                                                                                                                                                                                                                                     |
| 36  | V_BCKP | I   | When the main power supply VCC is cut off, V_BCKP supplies power to RTC and relevant register. Level requirement: 2.0 V ~ 3.6 V, and the working current is less than 60 μA at 25 °C. If you do not use the hot start function, connect V_BCKP to VCC. Do NOT connect it to ground or leave it floating. |

| No. | Pin     | I/O | Description                                                            |
|-----|---------|-----|------------------------------------------------------------------------|
| 37  | GND     | —   | Ground                                                                 |
| 38  | NC      | —   | No connection inside; leave floating                                   |
| 39  | NC      | —   | No connection inside; leave floating                                   |
| 40  | NC      | —   | No connection inside; leave floating                                   |
| 41  | GND     | —   | Ground                                                                 |
| 42  | TXD1    | O   | COM1 output, LVTTTL                                                    |
| 43  | RXD1    | I   | COM1 input, LVTTTL                                                     |
| 44  | SDA     | I/O | I <sup>2</sup> C data                                                  |
| 45  | SCL     | I/O | I <sup>2</sup> C clock                                                 |
| 46  | NC      | —   | No connection inside; leave floating                                   |
| 47  | NC      | —   | No connection inside; leave floating                                   |
| 48  | GND     | —   | Ground                                                                 |
| 49  | RESET_N | I   | System reset; active Low. The active time should be no less than 5 ms. |
| 50  | NC      | —   | No connection inside; leave floating                                   |
| 51  | EVENT   | I   | Event mark input, with adjustable frequency and polarity               |
| 52  | NC      | —   | No connection inside; leave floating                                   |
| 53  | PPS     | O   | Pulse per second, with adjustable pulse width and polarity             |
| 54  | NC      | —   | No connection inside; leave floating                                   |

## 2.2 Electrical Specifications

### 2.2.1 Absolute Maximum Ratings

Table 2-2 Absolute Maximum Ratings

| Parameter                 | Symbol             | Min. | Max. | Unit |
|---------------------------|--------------------|------|------|------|
| Power Supply Voltage      | VCC                | -0.3 | 3.6  | V    |
| Input Voltage             | V <sub>in</sub>    | -0.3 | 3.6  | V    |
| GNSS Antenna Signal Input | ANT_IN             | -0.3 | 6    | V    |
| Antenna RF Input Power    | ANT_IN input power |      | +10  | dBm  |
| External LNA Power Supply | VCC_RF             | -0.3 | 3.6  | V    |
| VCC_RF Output Current     | ICC_RF             |      | 100  | mA   |
| Storage Temperature       | T <sub>stg</sub>   | -55  | 95   | °C   |

## 2.2.2 Operating Conditions

Table 2-3 Operating Conditions

| Parameter                         | Symbol           | Min. | Typ.    | Max. | Unit | Condition |
|-----------------------------------|------------------|------|---------|------|------|-----------|
| Power Supply Voltage <sup>7</sup> | VCC              | 3.0  | 3.3     | 3.6  | V    |           |
| Maximum VCC Ripple                | V <sub>rpp</sub> | 0    |         | 50   | mV   |           |
| Working Current <sup>8</sup>      | I <sub>opr</sub> |      | 145     | 180  | mA   | VCC=3.3 V |
| VCC_RF Output Voltage             | VCC_RF           |      | VCC-0.1 |      | V    |           |
| VCC_RF Output Current             | ICC_RF           |      |         | 50   | mA   |           |
| Operating Temperature             | T <sub>opr</sub> | -40  |         | 85   | °C   |           |
| Power Consumption                 | P                |      | 480     |      | mW   |           |

## 2.2.3 IO Threshold

Table 2-4 IO Threshold

| Parameter                 | Symbol                | Min.          | Typ. | Max.         | Unit | Condition               |
|---------------------------|-----------------------|---------------|------|--------------|------|-------------------------|
| Low Level Input Voltage   | V <sub>in_low</sub>   | 0             |      | 0.6          | V    |                         |
| High Level Input Voltage  | V <sub>in_high</sub>  | VCC ×<br>0.7  |      | VCC +<br>0.2 | V    |                         |
| Low Level Output Voltage  | V <sub>out_low</sub>  | 0             |      | 0.45         | V    | I <sub>out</sub> = 2 mA |
| High Level Output Voltage | V <sub>out_high</sub> | VCC -<br>0.45 |      | VCC          | V    | I <sub>out</sub> = 2 mA |

<sup>7</sup> The voltage range of VCC (3.0 V ~ 3.6 V) has already included the ripple voltage.

<sup>8</sup> Since the product has capacitors inside, inrush current occurs during power-on. You should evaluate in the actual environment in order to check the effect of the supply voltage drop caused by inrush current in the system.

## 2.2.4 Antenna Feature

Table 2-5 Antenna Feature

| Parameter          | Symbol           | Min. | Typ. | Max. | Unit | Condition |
|--------------------|------------------|------|------|------|------|-----------|
| Optimum Input Gain | G <sub>ant</sub> | 18   | 30   | 36   | dB   |           |

## 2.3 Dimensions

Table 2-6 Dimensions

| Parameter | Min. (mm) | Typ. (mm) | Max. (mm) |
|-----------|-----------|-----------|-----------|
| A         | 21.80     | 22.00     | 22.50     |
| B         | 16.80     | 17.00     | 17.50     |
| C         | 2.40      | 2.60      | 2.80      |
| D         | 3.75      | 3.85      | 3.95      |
| E         | 0.95      | 1.05      | 1.15      |
| F         | 1.80      | 1.90      | 2.00      |
| G         | 1.00      | 1.10      | 1.20      |
| H         | 0.70      | 0.80      | 0.90      |
| K         | 1.40      | 1.50      | 1.60      |
| M         | 3.55      | 3.65      | 3.75      |
| N         | 3.15      | 3.25      | 3.35      |
| P         | 2.00      | 2.10      | 2.20      |
| R         | 1.00      | 1.10      | 1.20      |
| X         | 0.72      | 0.82      | 0.92      |

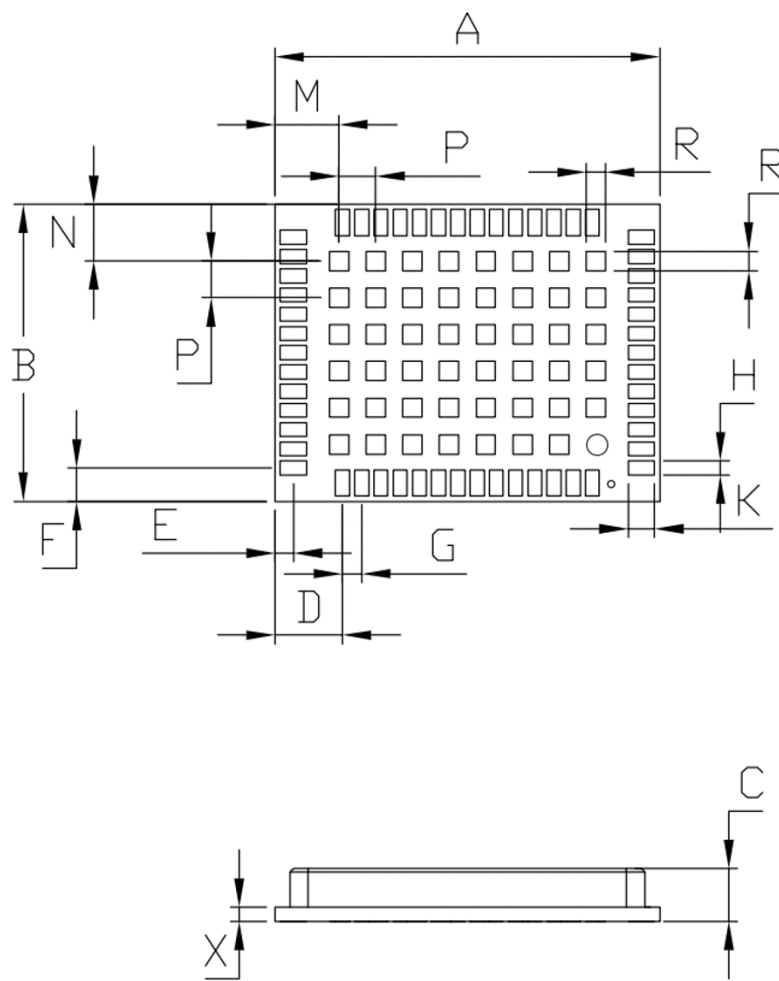
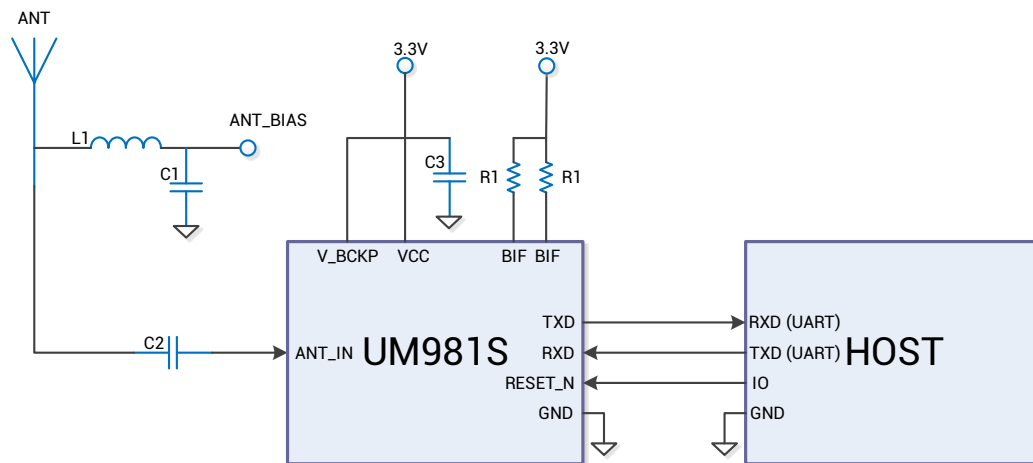


Figure 2-2 UM981S Mechanical Dimensions

## 3 Hardware Design

### 3.1 Recommended Minimal Design



**Figure 3-1 Recommended Minimal Design**

L1: 68 nH RF inductor in 0603 package is recommended

C1: 100 nF + 100 pF capacitors connected in parallel is recommended

C2: 100 pF capacitor is recommended

C3:  $N \times 10 \mu\text{F} + 1 \times 100 \text{ nF}$  capacitors connected in parallel is recommended, and the total inductance should be no less than  $30 \mu\text{F}$

R1: 10 k $\Omega$  resistor is recommended

## 3.2 Antenna Feed Design

UM981S supports feeding the antenna from the outside of the module rather than from the inside. It is recommended to use devices with high power and that can withstand high voltage. Gas discharge tube, varistor, TVS tube and other high-power protective devices may also be used in the power supply circuit to further protect the module from lightning strike and surge.

**⚠** If the antenna feed supply ANT\_BIAS and the module's main supply VCC use the same power rail, the ESD, surge and overvoltage from the antenna will have an effect on VCC, which may cause damage to the module. Therefore, it is recommended to design an independent power rail for the ANT\_BIAS to reduce the possibility of module damage.

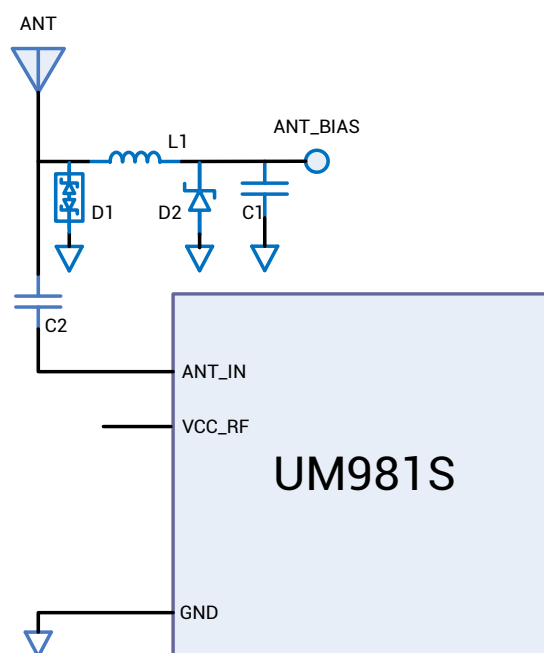


Figure 3-2 UM981S External Antenna Feed Reference Circuit

**Notes:**

1. L1: feed inductor, 68 nH RF inductor in 0603 package is recommended
2. C1: decoupling capacitor, recommended to connect two capacitors of 100 nF/100 pF in parallel
3. C2: DC blocking capacitor, recommended 100 pF capacitor

4. It is not recommended to use VCC\_RF as ANT\_BIAS to feed the antenna (VCC\_RF has not been optimized for anti-lightning strike, anti-surge and over current protection due to the compact size of the module)
5. D1: ESD diode, choose the ESD protection device that supports high frequency signals (above 2000 MHz)
6. D2: TVS diode, choose a TVS diode with appropriate clamping specification according to the requirement of feed voltage and antenna withstand voltage

### 3.3 Power-on and Power-off

#### VCC

- The VCC initial level when power-on should be less than 0.4 V.
- The VCC ramp when power-on should be monotonic, without plateaus.
- The voltages of undershoot and ringing should be within 5% VCC.
- Power-on time interval: The time interval between the power-off ( $V_{CC} < 0.4\text{ V}$ ) to the next power-on must be larger than 500 ms.

#### V\_BCKP

- The V\_BCKP initial level when power-on should be less than 0.4 V.
- The V\_BCKP ramp when power-on should be monotonic, without plateaus.
- The voltages of undershoot and ringing should be within 5% V\_BCKP.
- Power-on time interval: The time interval between the power-off ( $V_{BCKP} < 0.4\text{ V}$ ) to the next power-on must be larger than 500 ms.

### 3.4 Grounding and Heat Dissipation

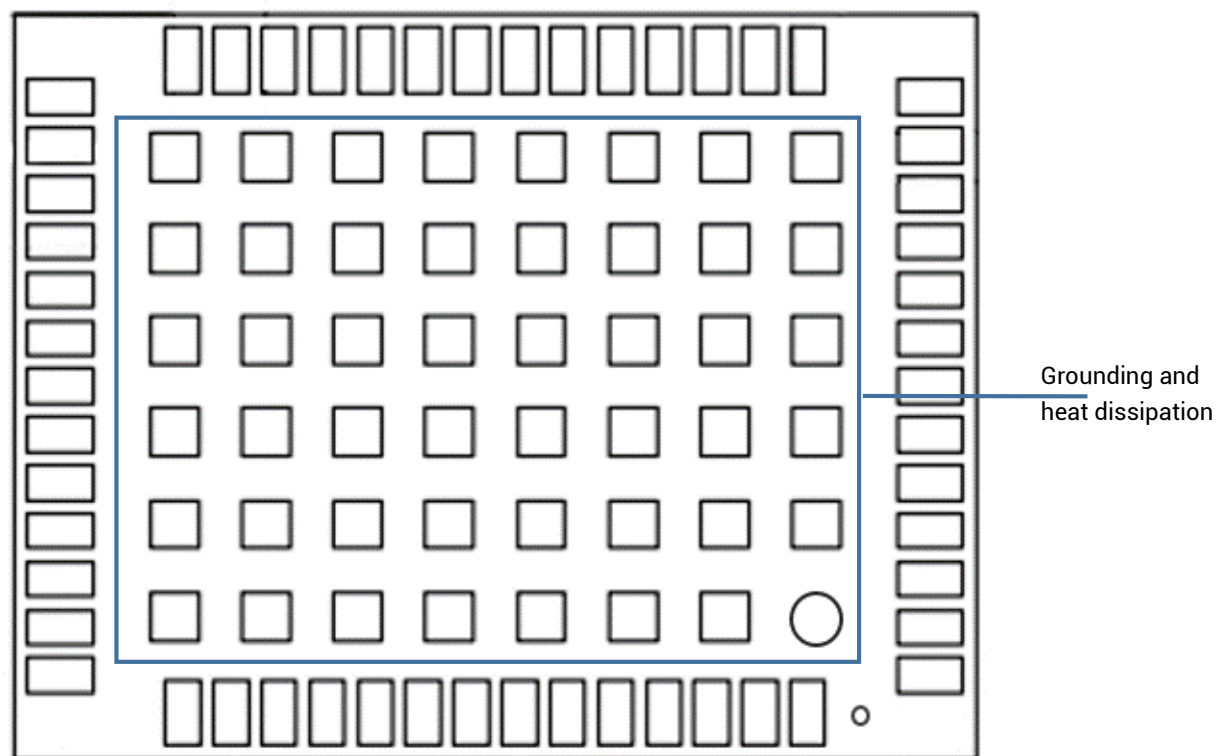


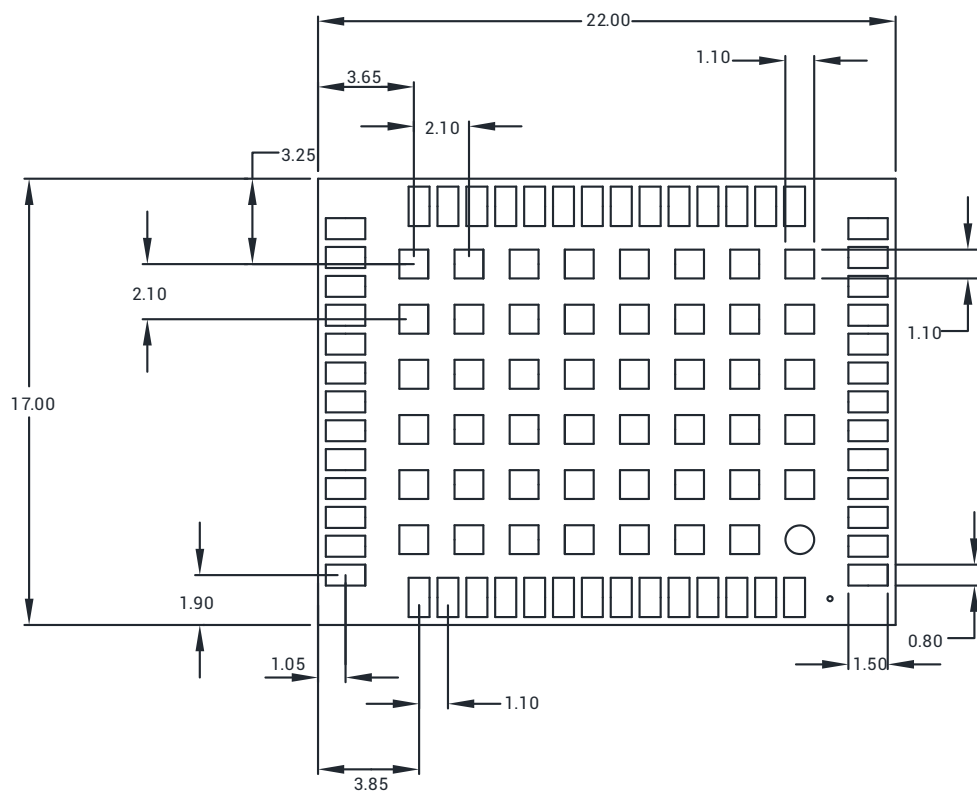
Figure 3-3 Grounding and Heat Dissipation Pad (Bottom View)

The 48 pads in the rectangle area are used for grounding and heat dissipation. In the PCB design, the pads should be connected to a large-size ground to strengthen the heat dissipation.

### 3.5 Recommended Footprint on the PCB

The dimensions of UM981S' footprint on the PCB is recommended to be the same as that of the module's pads, as shown in **Figure 3-4 Recommended Footprint**. For more information about the module's dimensions, see **2.3 Dimensions**.

- ☞ For the convenience of hardware testing and debugging, proper test points can be added for the functional pins of the module.
- ☞ The dimensions of PCB pads can be optimized according to the specific production process to ensure manufacturability and reliability.



**Figure 3-4 Recommended Footprint (Unit: mm)**

## 4 Production Requirements

Recommended soldering temperature curve is as follows:

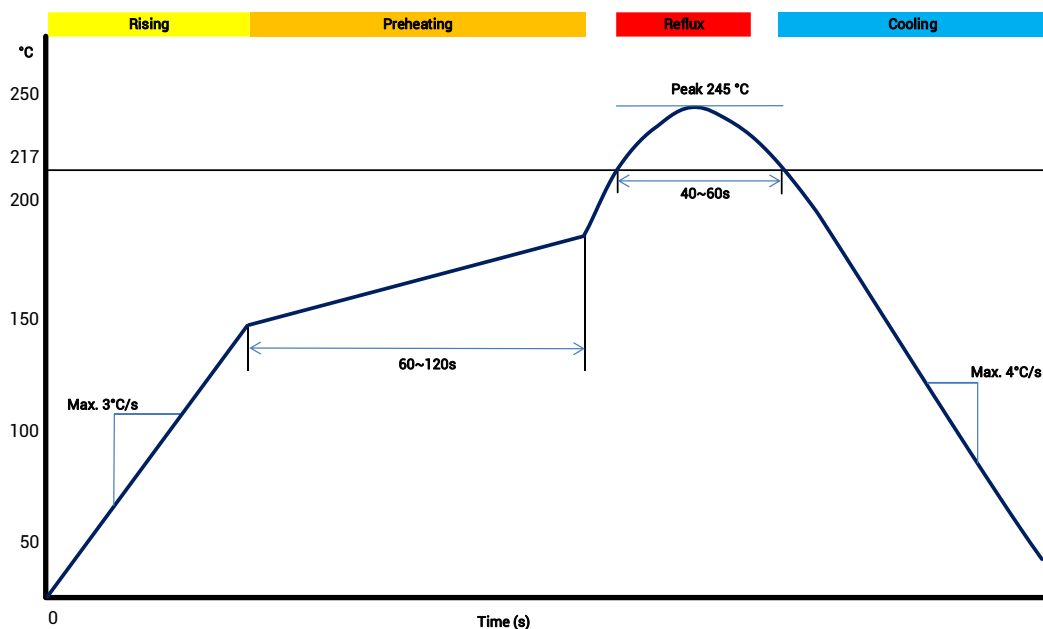


Figure 4-1 Soldering Temperature (Lead-free)

### Temperature Rising Stage

- Rising slope: Max. 3 °C/s
- Rising temperature range: 50 °C ~ 150 °C

### Preheating Stage

- Preheating time: 60s ~ 120 s
- Preheating temperature range: 150 °C ~ 180 °C

### Reflux Stage

- Over melting temperature (217 °C) time: 40s ~ 60 s
- Peak temperature for soldering: no higher than 245 °C

### Cooling Stage

- Cooling slope: Max. 4 °C / s



- In order to prevent falling off during soldering of the module, do not solder it on the back of the board during design, and it is not recommended to go through soldering cycle twice.

- The setting of soldering temperature depends on many factors of the factory, such as board type, solder paste type, solder paste thickness etc. Please also refer to the relevant IPC standards and indicators of solder paste.
  - Since the lead soldering temperature is relatively low, if using this method, please give priority to other components on the board.
  - The opening of the stencil needs to meet your design requirement and comply with the examine standards. The thickness of the stencil is recommended to be 0.15 mm (not less than 0.12 mm).
- 

 The design of the stencil can be optimized according to the specific production process to ensure manufacturability and reliability.

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## 5 Packaging

### 5.1 Label Description



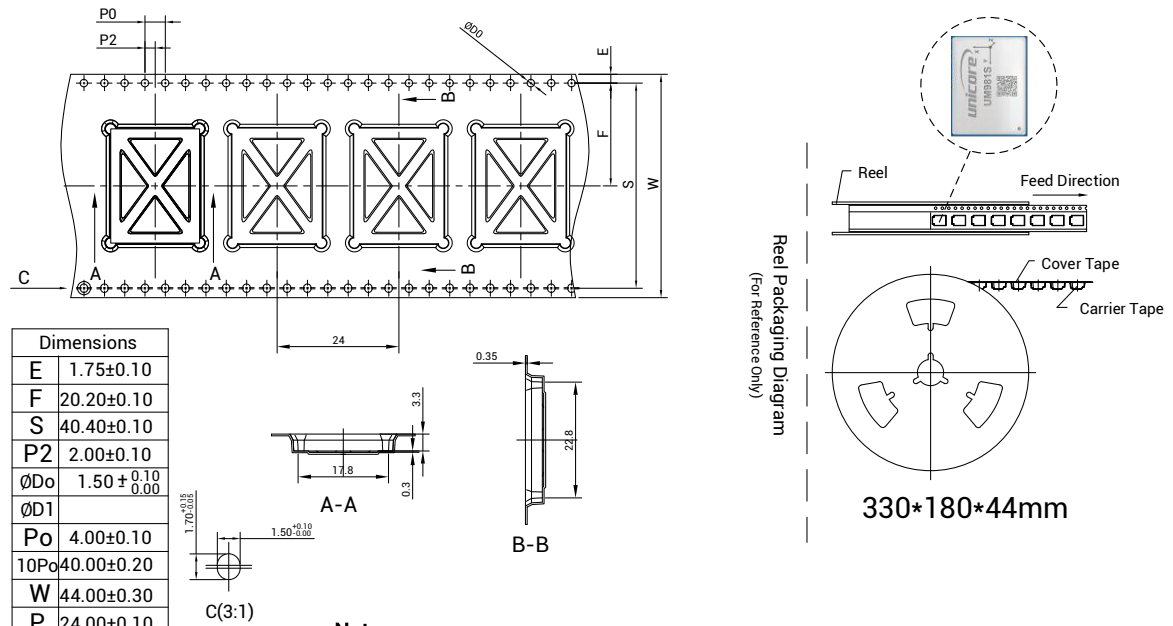
Figure 5-1 Label Description

### 5.2 Product Packaging

The UM981S module uses carrier tape and reel (suitable for mainstream surface mount devices), packaged in vacuum-sealed aluminum foil antistatic bags, with a desiccant inside to prevent moisture. When using reflow soldering process to solder modules, please strictly comply with IPC standard to conduct temperature and humidity control on the modules. As packaging materials such as the carrier tape can only withstand the temperature of 55 degrees Celsius, modules shall be removed from the package during baking.

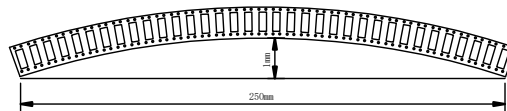


Figure 5-2 UM981S Package



**Note:**

1. The cumulative tolerance of 10 side holes should not exceed  $\pm 0.2$  mm.
2. Material of the tape: Black antistatic PS (surface impedance  $10^5$ - $10^{11}$ ) (surface static voltage <100 V), thickness: 0.35 mm.
3. Total length of the 13-inch reel package: 6.816 m (Length of the first part of empty packets: 0.408 m, length of packets containing modules: 6 m, length of the last part of empty packets: 0.408 m).
4. Total number of packets in the 13-inch reel package: 284 (Number of the first part of empty packets: 17; actual number of modules in the packets: 250; number of the last part of empty packets: 17).
5. All dimension designs are in accordance with EIA-481-C-2003.
6. The maximum bending degree of the carrier tape within the length of 250 mm should not exceed 1 mm (see the figure below).



**Figure 5-3 UM981S Reel Package Diagram**

**Table 5-1 Package Description**

| Item          | Description                                                                                                                                      |
|---------------|--------------------------------------------------------------------------------------------------------------------------------------------------|
| Module Number | 250 pieces/reel                                                                                                                                  |
| Reel Size     | Tray: 13"<br>External diameter: $330 \pm 2$ mm,<br>Internal diameter: $180 \pm 2$ mm,<br>Width: $44.5 \pm 0.5$ mm<br>Thickness: $2.0 \pm 0.2$ mm |

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| Item         | Description                                      |
|--------------|--------------------------------------------------|
| Carrier Tape | Space between (center-to-center distance): 24 mm |

Before surface mounting, make sure that the color of the 30% circle on the HUMIDITY INDICATOR is blue (see Figure 5-4). If the color of the 20% circle is pink and the color of the 30% circle is lavender (see Figure 5-5), you must bake the module until it turns to blue. The UM981S is rated at MSL level 3. Please refer to the IPC/JEDEC J-STD-033 standards for the package and operation requirements. You may also access to the website [www.jedec.org](http://www.jedec.org) to get more information.

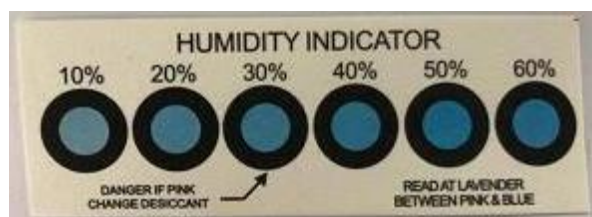


Figure 5-4 Normal Humidity Indication

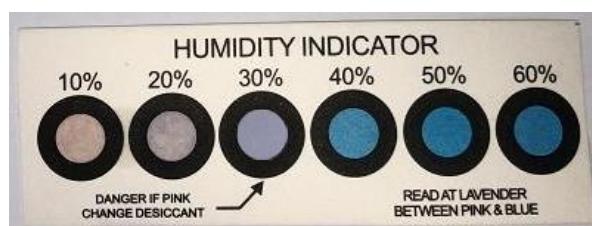


Figure 5-5 Abnormal Humidity Indication

The shelf life of the UM981S module packaged in vacuum-sealed aluminum foil antistatic bags is one year.

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